

Empowering Citizens. Smarter Societies.

**Insight**  
Centre for Data Analytics



# Understanding traffic through video analytics from instrumented vehicles

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A World Leading SFI Research Centre



NUI Galway  
OÉ Gaillimh



## Cloud-LSVA



Large-Scale Video Analytics

Annotation & search of video data for ADAS & cartography

H2020 ICT “Big Data”



## VI-DAS



Vision Inspired Driver Assistance System

Object tracking & path prediction for safer driving

H2020 Mobility





~15-20 TB/day  
~300 hrs /minute

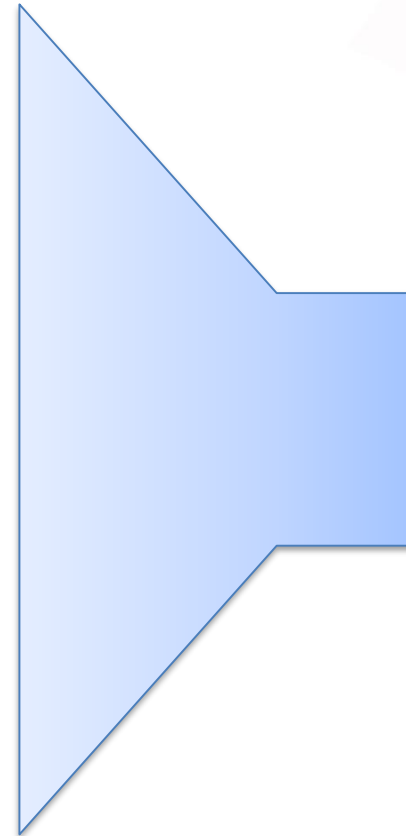
Lossy content  
Large amount of files  
Worldwide upload points



ADAS Context  
Open-road Acquisition

~10-50 TB/day/vehicle  
~8 hr collection window

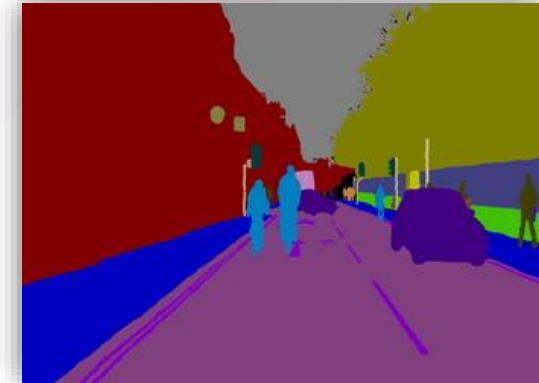
Lossless content  
Reduced amount of files  
Limited upload points



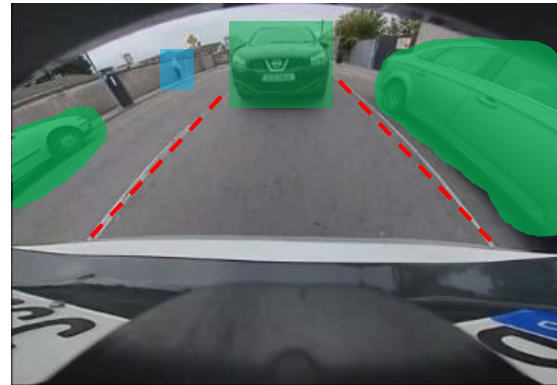
# Big Data

Volume  
Velocity  
Variety

Augmented Segmentation  
Semi-automatic Annotation  
Semantic Segmentation



Object Detection, Classification & Tracking  
Path Prediction



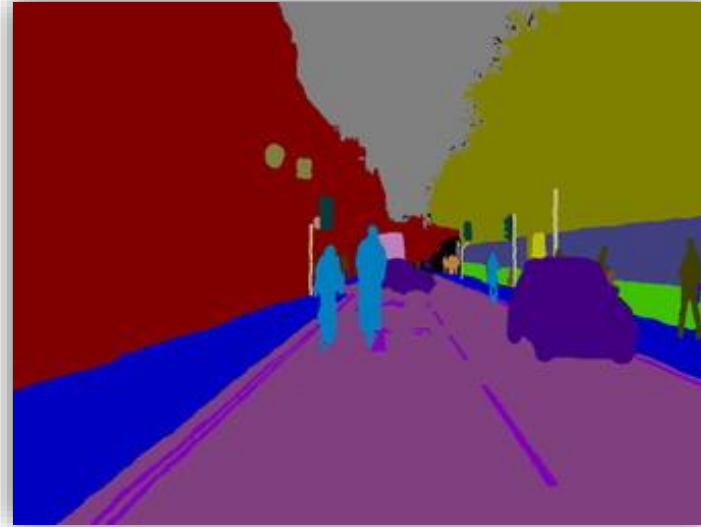
Situation Assessment  
Semantic Search

## Understanding high-volume, high-speed multimedia data – a computer scientist's view

- Big data in ADAS means fully manual annotation is infeasible
- Data that's not annotated is not usable
- Annotation via Machine Learning?
- Deep learning: a step change in computer vision

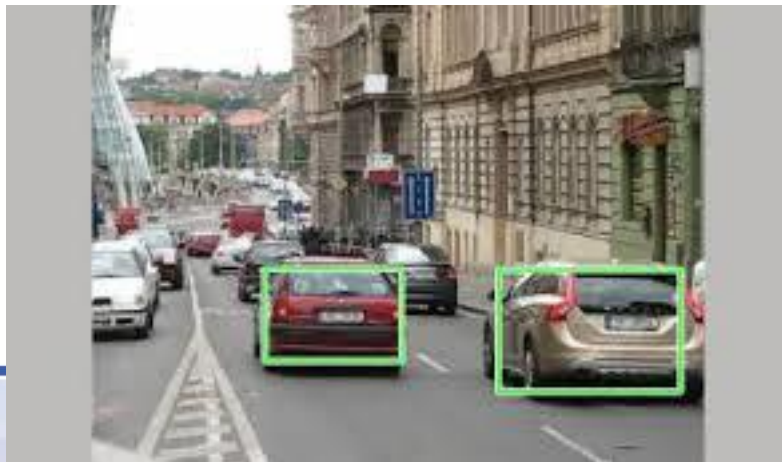


Road scene



Ground-truth

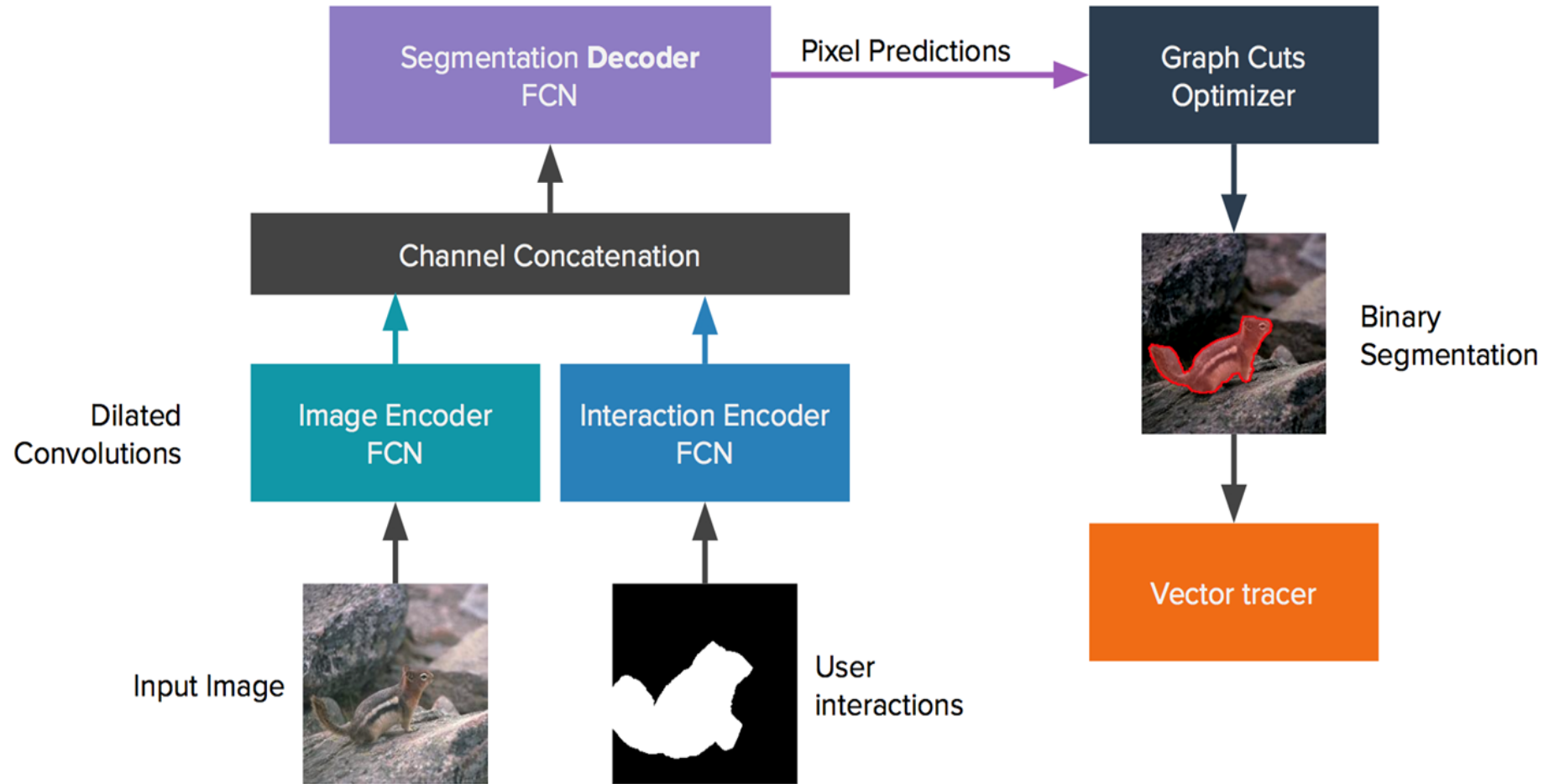
Scene level  
Static Objects  
Dynamic Objects  
Background  
Actors  
Vehicles



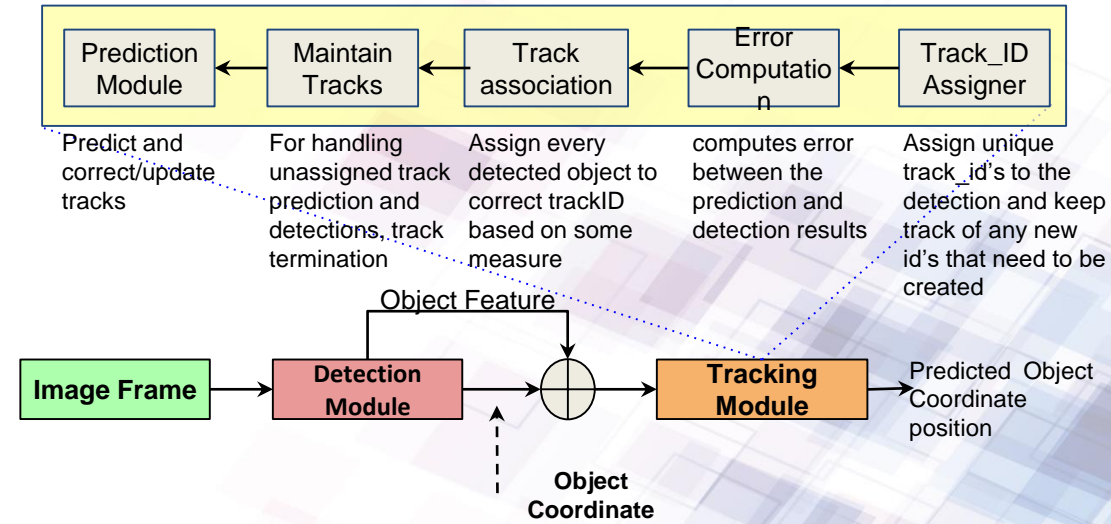
Void	Building	Wall	Tree	VegetationMisc
Fence	Sidewalk	ParkingBlock	Column_Pole	TrafficCone
Bridge	SignSymbol	Misc_Text	TrafficLight	Sky
Tunnel	Archway	Road	RoadShoulder	LaneMkgsDriv
LaneMkgsNonDriv	Animal	Pedestrian	Child	CartLuggagePran
Bicyclist	MotorcycleScooter	Car	SUVPickupTruck	Truck_Bus
Train	OtherMoving			

Classes

# Interactive Segmentation



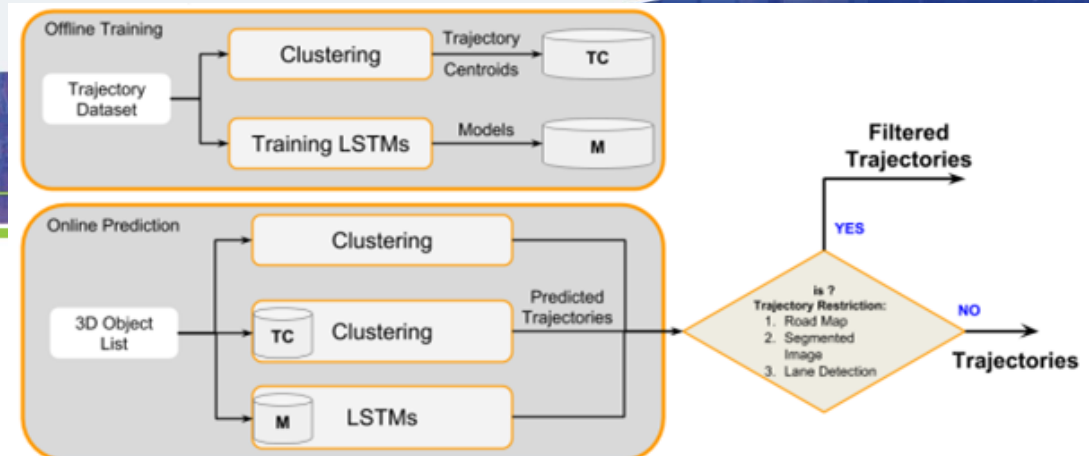
# Object Tracking





# Path Prediction

Prediction in autonomous vehicles is all about how the ego vehicle is going to predict the trajectory or path of the other vehicles or pedestrians



Ground Truth Tracklets



Prediction



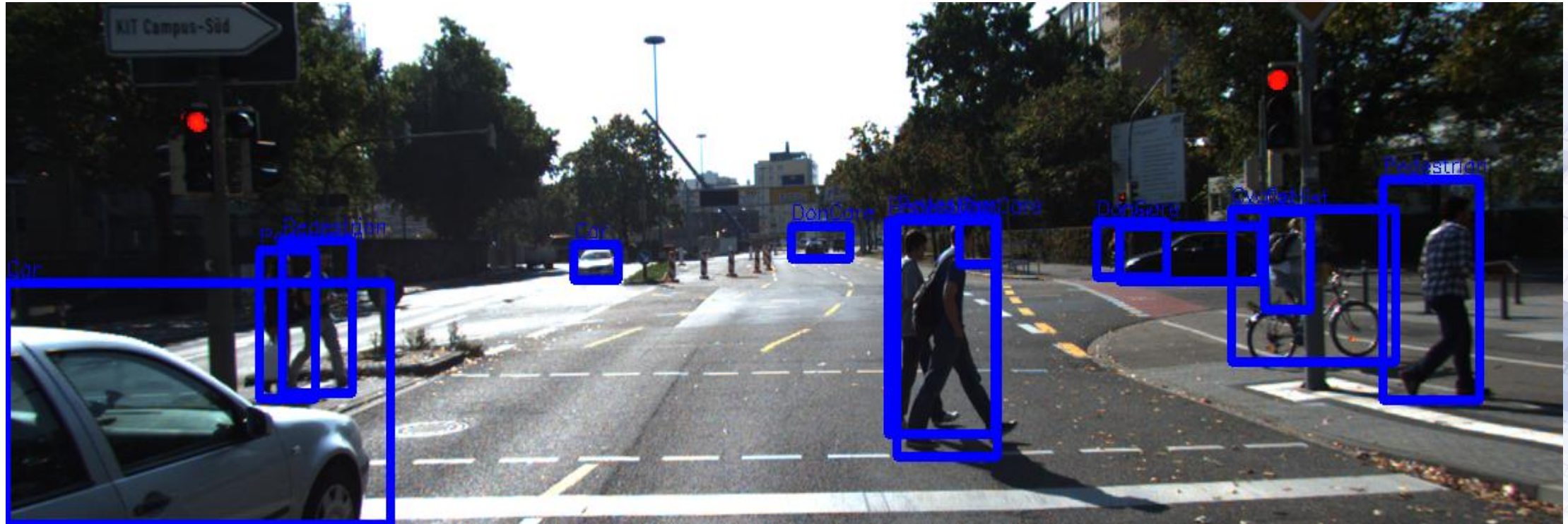
Ground Truth Tracklets



Prediction



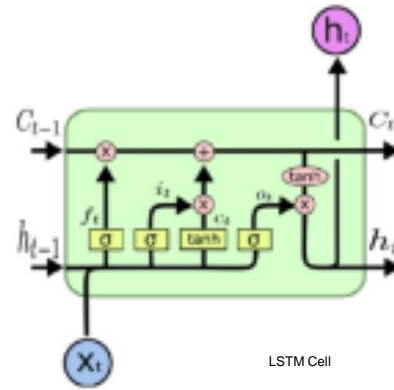
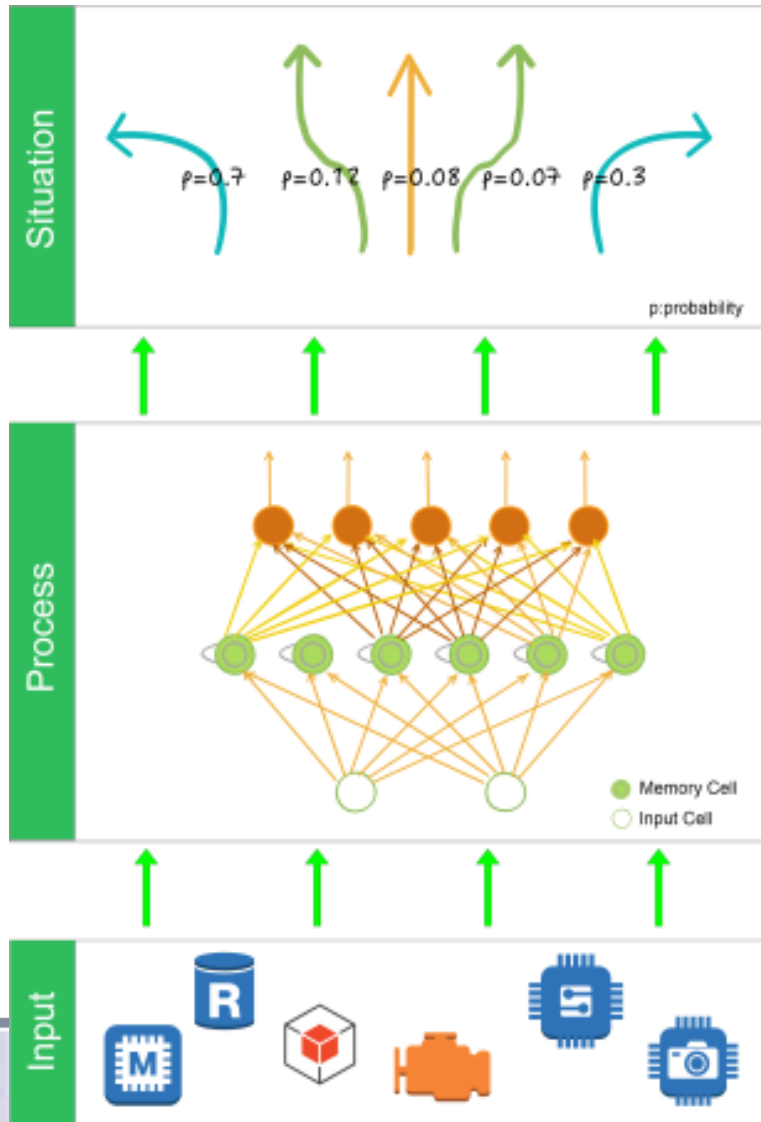
# Dynamic Object Path Prediction



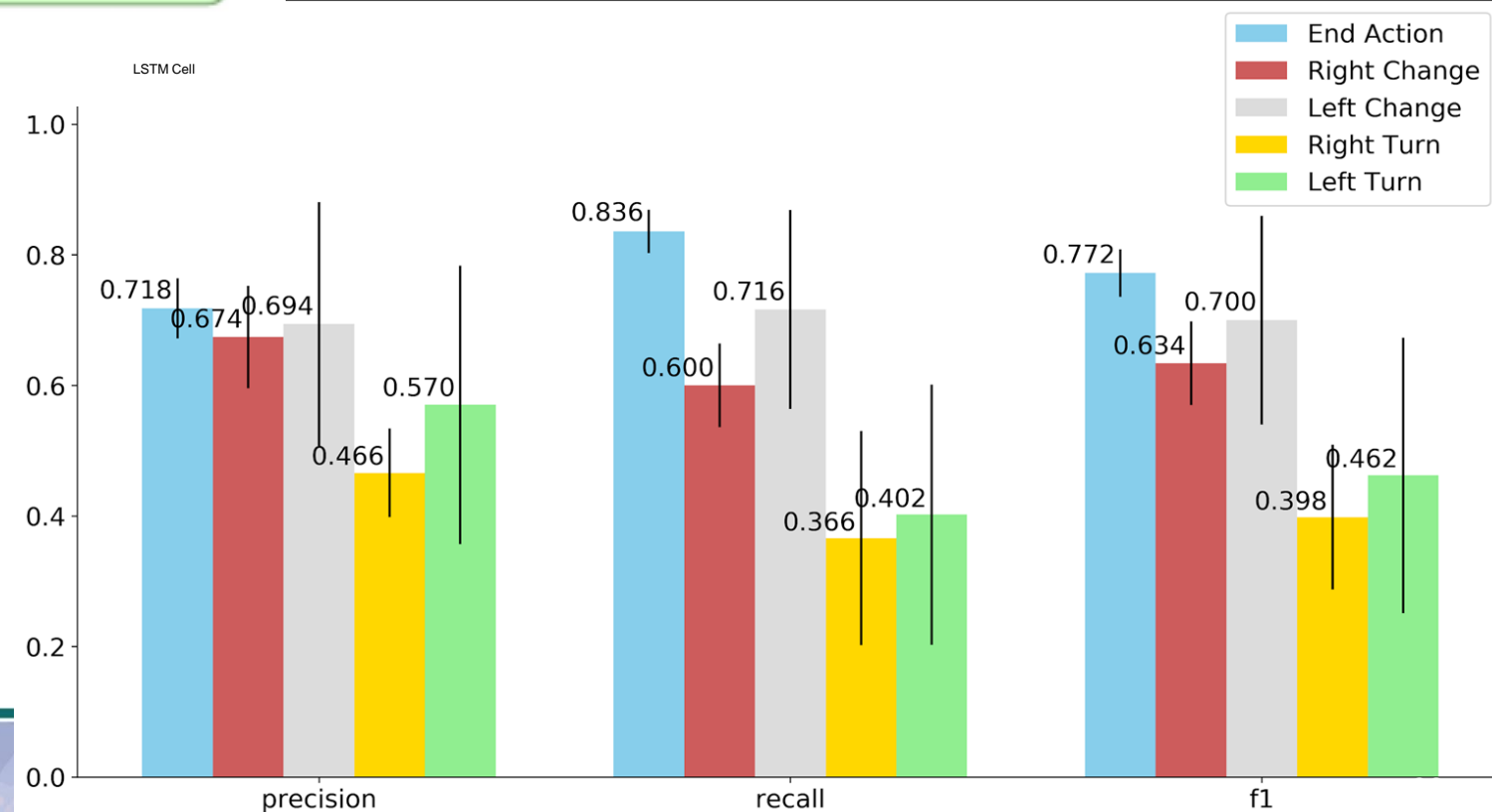
## Public perception of what drivers do in semi-autonomous vehicles



# Driver Behaviour Prediction



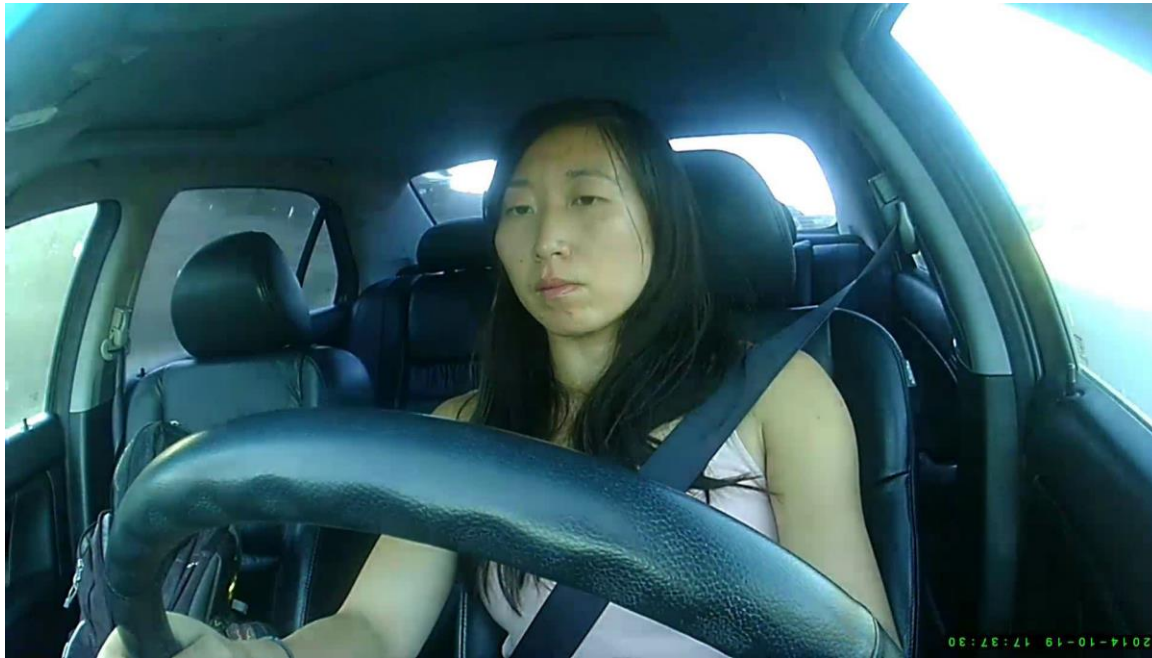
Driving Dynamic Classification Report (each action)



## Demo – Right Turn



## Demo – End Action



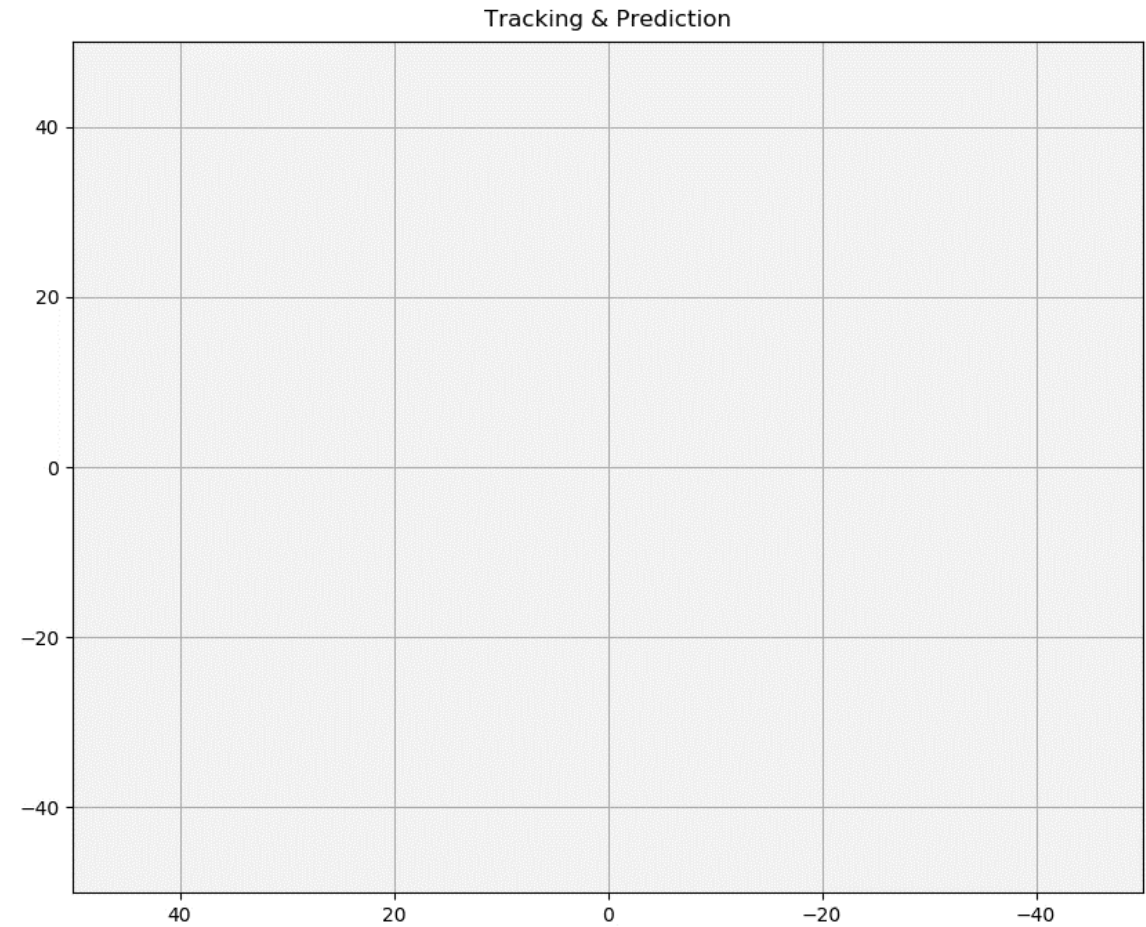
# Scenario Detection/Classification



## LIDAR point cloud Data

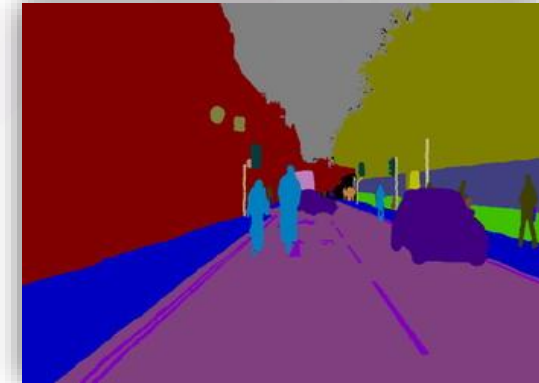


## Tracking and Prediction Results - Car Only

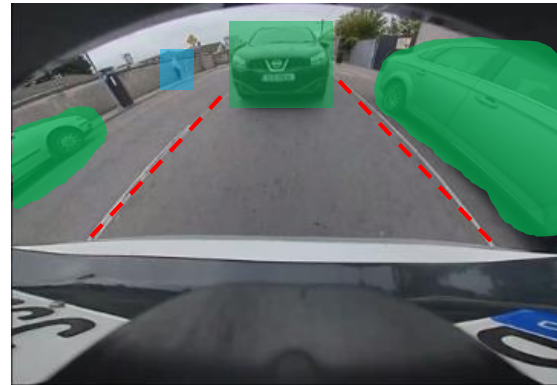




Augmented Segmentation  
Semi-automatic Annotation  
Semantic Segmentation



Object Detection, Classification & Tracking  
Path Prediction



Situation Assessment  
Semantic Search

- Availability
  - Good academic datasets: KITTI, NuScenes, CityScape, DeepDrive
  - NVidia AI City Challenge (<https://www.aicitychallenge.org/>)
- Annotations
  - Not always available
  - Not always sufficiently detailed (tracks, bounding box vs pixel-level segmentation)
- Variety
  - Synchronised Sensor Data (LIDAR, telemetry, GPS, etc.)
  - Context ...





Saleh, K., Hossny, M., & Nahavandi, S. (2018). Effective vehicle-based kangaroo detection for collision warning systems using region-based convolutional networks. *Sensors*, 18(6).

## Volvo's driverless cars 'confused' by kangaroos

🕒 27 June 2017

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Volvo's self-driving technology is struggling to identify kangaroos in the road.

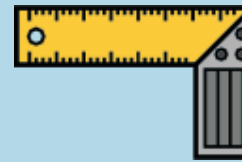
<https://www.bbc.com/news/technology-40416606>

# Key challenges

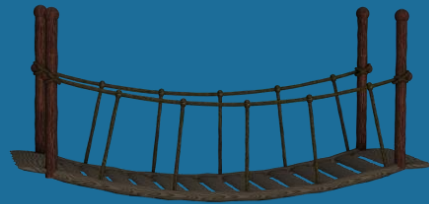
**Multimodal**



**Scalable**



**Transferable**



**Contextual**



# Thanks to ...

## Multimedia Analytics (Vehicle Data) Team at Insight DCU

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